

Generating time series with `glred`

M. A. Floyd T. A. Herring

Massachusetts Institute of Technology, Cambridge, MA, USA

GNSS Data Processing and Analysis with GAMIT/GLOBK and `track`

UNAVCO Headquarters, Boulder, Colorado, USA

24–28 August 2020

http://geoweb.mit.edu/~floyd/courses/gg/202008_UNAVCO/

Material from R. W. King, T. A. Herring, M. A. Floyd (MIT) and S. C. McClusky (now at ANU)

Post-processing: GLOBK

- Convert ASCII h-files to binary h-files (`htoglb` in `glbf/`)
- Generate and chronological list of binary h-files (`glist` in `gsoln/`)
- At this point, diverge in approach depending on solution sought
 - More details about `glred`, `globk` and `glorg` in advanced course lectures
- Similarly to `sh_gamit`, the batch script `sh_glred` will run all of the above command steps (and more, introduced in next slides)
 - User may just need to edit `globk` and/or `glorg` command files to achieve most desired types of solution

sh_glred

- `glred` is just a way of invoking `globk` to process one day at a time; `sh_glred` is a script to invoke `glred` easily for a sequence of days
- Once you've run `sh_gamit` for a sequence of days, you will have on each day an h-file of loosely constrained parameter estimates and covariances. If you have appropriately constructed command files for `globk` (`globk.cmd`) and `glorg` (`glorg.cmd`) in `[expt]/gsoln/`, you can obtain time series using, e.g.

```
sh_glred -expt [expt] -s [start yr] [start_doy] [stop yr] [stop doy] -opt H G T
```

which will translate the GAMIT plain text h-files into GLOBK binary h-files (H), run GLOBK (G) and run `sh_plot_pos` (T)

- Self-guided templates will guide you in constructing the command files (`~/gg/tables/globk.cmd` and `~/gg/tables/glorg.cmd`)

Manual sequence

- `htoglb` (i.e. `sh_glred -opt H`)
 - Converts plain text h-files output from GAMIT to binary h-files (in `glbf/`) for input to GLOBK
- `ls`
 - Create list of binary h-files to process (in `gsoln/`)
- `glist`
 - Create chronological list of h-files to process and associated information
- `glred` (i.e. `sh_glred -opt G`)
 - Create “.org”-file(s) with individual solutions
- `sh_plot_pos` (i.e. `sh_glred -opt T`)
 - Create “.pos” (time series) file(s) and time series plots
- `globk`
 - Create combined (or velocity) solution
- `glorg`
 - Additional `glorg` runs for different reference frames

htoglb

- Creates binary h-files for input to GLOBK
 - All metadata etc. carried forward from GAMIT
- Not restricted to plain text h-files from GAMIT
 - May also use SINEX (Software INdependent EXchange format), GIPSY's "stacov" files, etc.
 - But beware of constraints implicit in solutions from other software/processing runs!
- For example, from glbf/

```
htoglb . ' ' ../[0-3][0-9][0-9]/h*a.*
```

- (Use pair of quotes " if no satellite data is to be saved. This is normal case).

GLOBK checks

- List files to be processed by GLOBK, e.g. from gsoln/
`ls ../glbf/h*.glx > expt.glx.gdl`
- Run pre-processing checks using `glist`

```
glist expt.glx.gdl 201407_NSFBay.sum +1 ~/gg/tables/itrf08_comb.eq:A 201407_NSFBay.gdl
```

- This will also calculate if any overlapping h-files should be combined with `glred` (e.g. multiple networks on the same day)
- Inspect any errors (e.g. site name clashes)

Create time series

- `glred` simply runs the main program, `globk`, once per interval (e.g. daily) to combine data over that interval into one solution and one effective time series point

```
glred 6 glred_20150811.prt glred_20150811.log 201407_NSFBay.gdl globk.cmd
```

- Assess solution by looking at “POS STATISTICS” lines
- Old example (Example 2 on this course’s web page) using `sh_glred` with “-opt E” creates:
 - “mb”-files (time series) with `multibase`
 - “psbase”-files (PostScript) with `sh_baseline`
- Updated, preferred method is `sh_glred` with “-opt T”:
 - `tssum` to create “.pos”-files (time series) from “.org”-file output from `glred`
 - `sh_plot_pos` to create PostScript plots
 - “.org”-file may be input to `sh_plot_pos`, which will run `tssum` for you, e.g.
`sh_plot_pos -f glred_YYYYMMDD.org -d _YYYYMMDD ...`

Time series solution files

Old scheme

- “.org”-file
- ensum
 - “VAL”-file (time series values)
 - “SUM”-file (statistics)
- multibase
 - “mb”-files
- sh_baseline
 - Time series plots

sh_plotcrd

Current scheme

- “.org”-file
- tssum
 - “.pos”-files
 - tsfit
 - “.res”-files
- sh_plot_pos
 - Time series plots

sh_plot_pos

Recommended strategy for stabilization

- In the template files, `globk.cmd` and `glorg.cmd`:
 - default apr-file is `~/gg/tables/igb14_comb.apr`
 - default eq-file is `~/gg/tables/igb14_comb.eq`
 - default stab-file is `~/gg/tables/igb14_comb.stab_site`
- `igb14_comb.apr` is a combined .apr-file, using many publicly available coordinate sources, all aligned to ITRF2014
- `igb14_comb.eq` is the associated .eq-file with defined discontinuities
 - equipment changes
 - earthquakes
 - etc.
- `igb14_hierarchy.stab_site` uses the established IGS core network hierarchy to choose stabilizing sites, e.g.
 - `stab_site DRAO/BREW/NANO/ALBH/HOLB`
means use DRAO if available in the solution (e.g. h-files), otherwise use BREW if available, otherwise use NANO, etc.
- Equivalent files for previous realizations of ITRF2014 (“`itrf2014...`”, “`igs14...`”) and ITRF2008 (“`itrf08...`”, “`igb08...`”) still available

Inspect consistency of stabilization statistically

- It is a good idea to have thought about your reference frame stabilization when setting up your experiment, e.g. sites.defaults, before running `sh_gamit`
- Desire as many well-defined (e.g. IGS) sites as possible for redundancy
 - Recommended to use some of the sites (preferring the first column) in `~/gg/tables/igb14_hierarchy.stab_site` when selecting your processing network, e.g. additional sites listed in your sites.defaults
 - But remember trade-off with processing time, e.g. processing time scales proportionally to n^3

```
grep '^POS S' glred_20150811.org
```

```
POS STATISTICS: For 51 RefSites WRMS ENU 2.15 2.55 6.19 mm NRMS ENU 0.71 0.84 0.63 L0104260000_tg1a.glx
POS STATISTICS: For 54 RefSites WRMS ENU 2.17 2.42 6.03 mm NRMS ENU 0.74 0.80 0.63 L0104270000_tg1a.glx
POS STATISTICS: For 50 RefSites WRMS ENU 2.12 2.25 6.34 mm NRMS ENU 0.71 0.75 0.67 L0104280000_tg1a.glx
POS STATISTICS: For 54 RefSites WRMS ENU 2.19 2.31 5.23 mm NRMS ENU 0.80 0.81 0.58 L0104300000_tg1a.glx
POS STATISTICS: For 54 RefSites WRMS ENU 1.83 2.17 6.34 mm NRMS ENU 0.64 0.75 0.68 L0105010000_tg1a.glx
POS STATISTICS: For 54 RefSites WRMS ENU 2.09 2.63 6.47 mm NRMS ENU 0.80 0.98 0.75 L0105020000_tg1a.glx
```

“.pos”-files

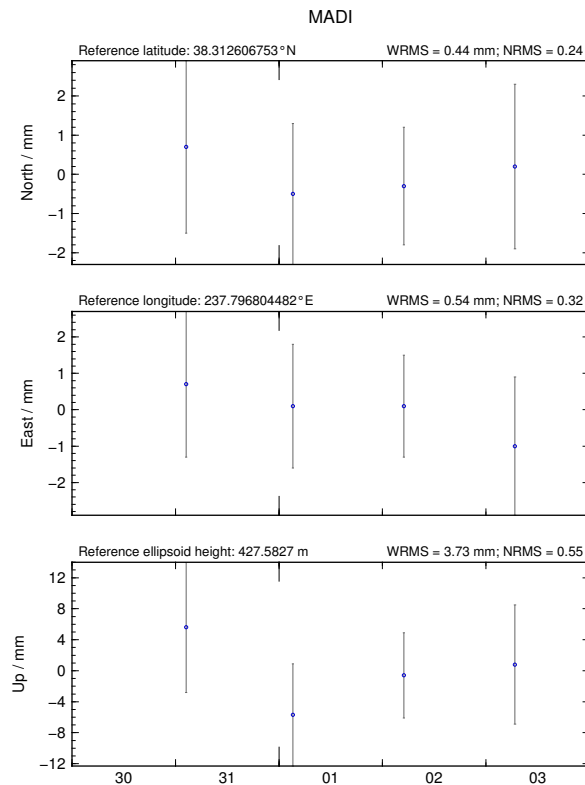
- These contain your time series solution
- Long format in various coordinate systems
 - Geocentric (X, Y, Z)
 - Geodetic (lon., lat., height)
 - Local (east, north, up)
- Can be input to `tsfit` (interactive version of GGMatlab tool “tsview”), `sh_cats` (requires CATS) and `sh_hector` (requires Hector)
- Both “.pos”-files and “.res”-files can be plotted with `sh_plot_pos`

sh_plot_pos

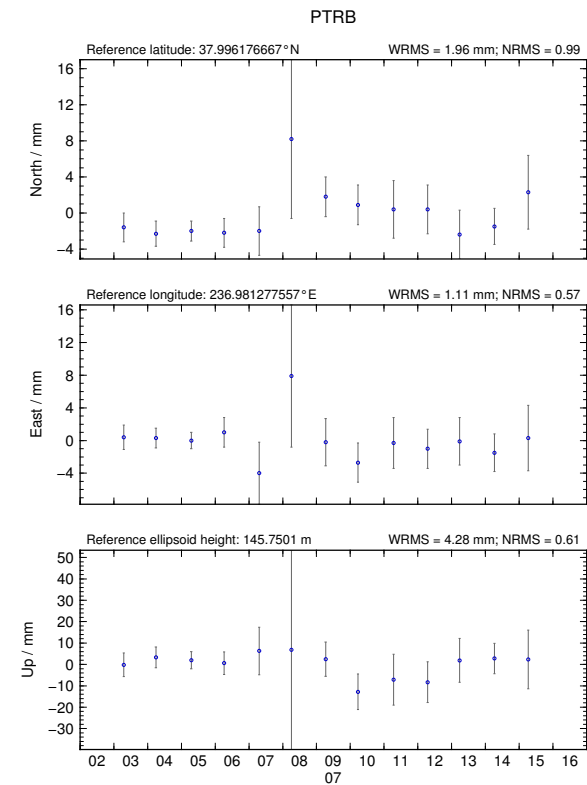
- Uses GMT and has many features including options to:
 - Read in “.org”-files, “.pos”-files (output of `tssum`) and “.res”-files (output of `tsfit`) [`-f` option]
 - Run `tsfit` (GLOBK’s curve-fitting module) on input “.pos”-files [`-t` option]
 - Calculate basic statistics (e.g. WRMS, NRMS)
 - Add vertical lines at epochs specified by renames, earthquakes or user [`-b`, `-e` and `-l` options, respectively]
 - Specify fixed start and end times of time series [`-t1`, `-t2` options]
 - etc.

Inspect consistency of time series

Good repeatability



Outlier



Excluding outliers or segments of data

- Create “rename” file records and add to GLOBK command file’s “eq_file” option, e.g.

```
rename PTRB      PTRB_XPS h1407080610_nb4a
rename PTRB      PTRB_XPS 2014 07 07 18 00 2014 07 08 18 30
rename ABCD      ABCD_XCL 2013 07 08 00 00
```

- “XPS” will not exclude data from `glred` (so still visible in time series) but will exclude data from `globk` (combination or velocity solution)
- “XCL” will exclude data from all `glred` and `globk` runs

Iterating your solution

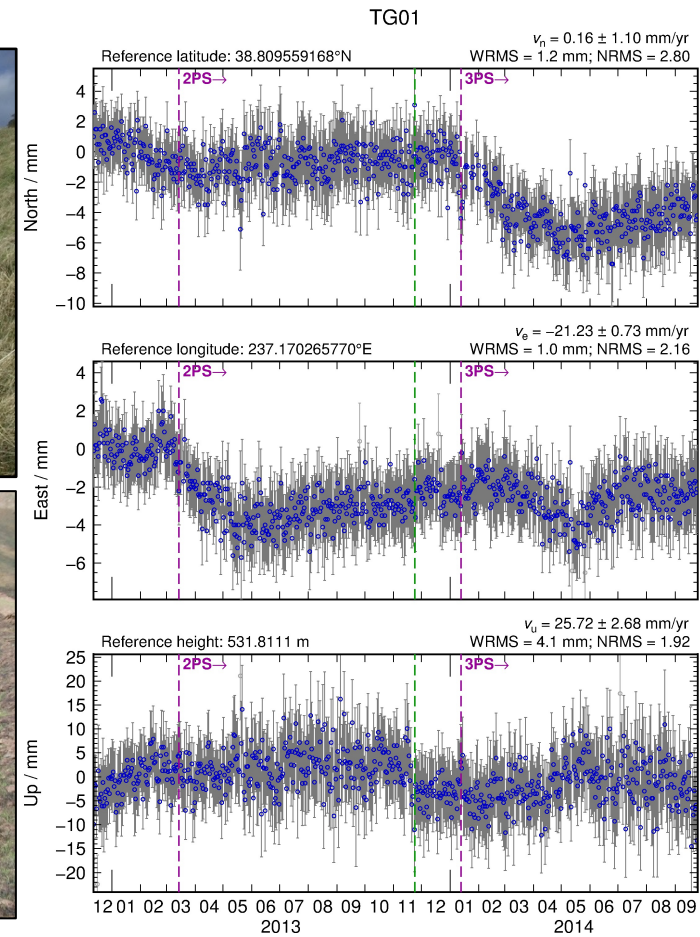
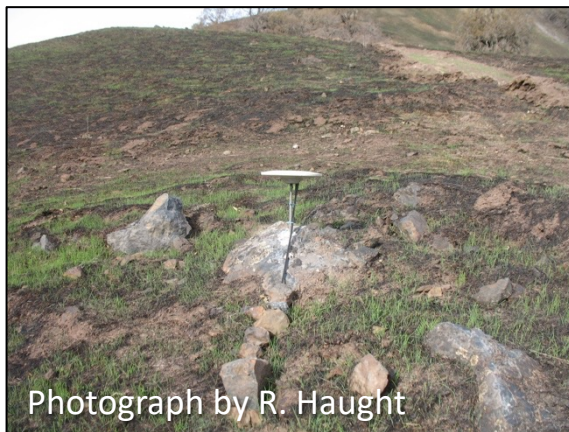
- First time series may only be stabilized by previously well-defined sites, e.g. ITRF sites
- Once a high-quality position (and velocity) estimate for a previously unknown or new site is available, we can use all sites to stabilize
- This approach may be used with both time series (e.g. `g1red`) and velocity (e.g. `g1obk`) solutions

Changes to equipment

- Antenna is main concern, although receiver may also affect continuity of calculated position
 - Even antennas of the same model type may not be manufactured within acceptable geodetic tolerance
- `stinf_to_rename` useful for creating automatic list



Changes in multipath environment

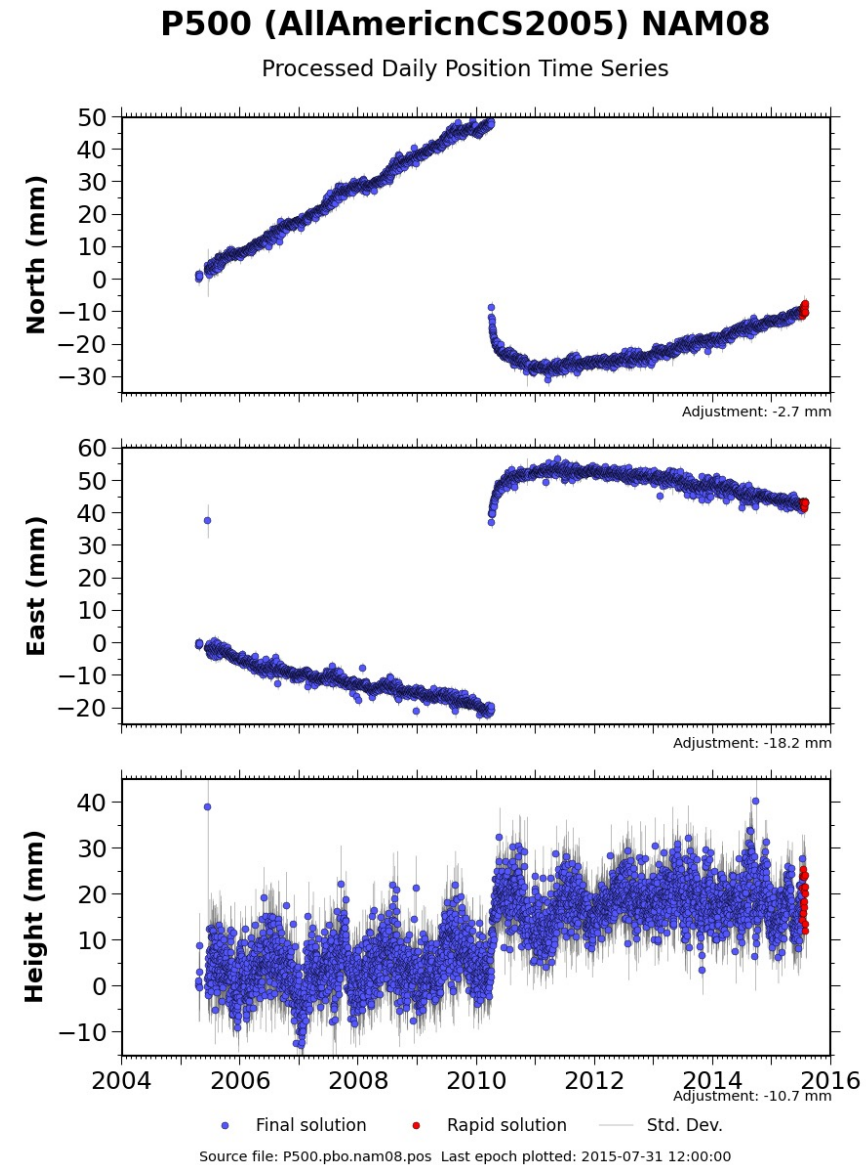


Rename scheme

- Rename scheme uses first character of suffix
 - XXXX_GPS → XXXX_2PS → XXXX_3PS → ... etc.
- Beyond “9PS”, convert to 10th letter of alphabet (“JPS”) and beyond
 - ... → XXXX_9PS → XXXX_JPS → XXXX_KPS → ... etc.
 - But remember “XPS” is a special case for excluding sites from gLobk runs
- For manual renames (e.g. due to manual inspection rather than known events), use 8 available letters in alphabet before “J”
 - XXXX_APS, XXXX_BPS, etc.
 - But remember “GPS” is a special case (the default)

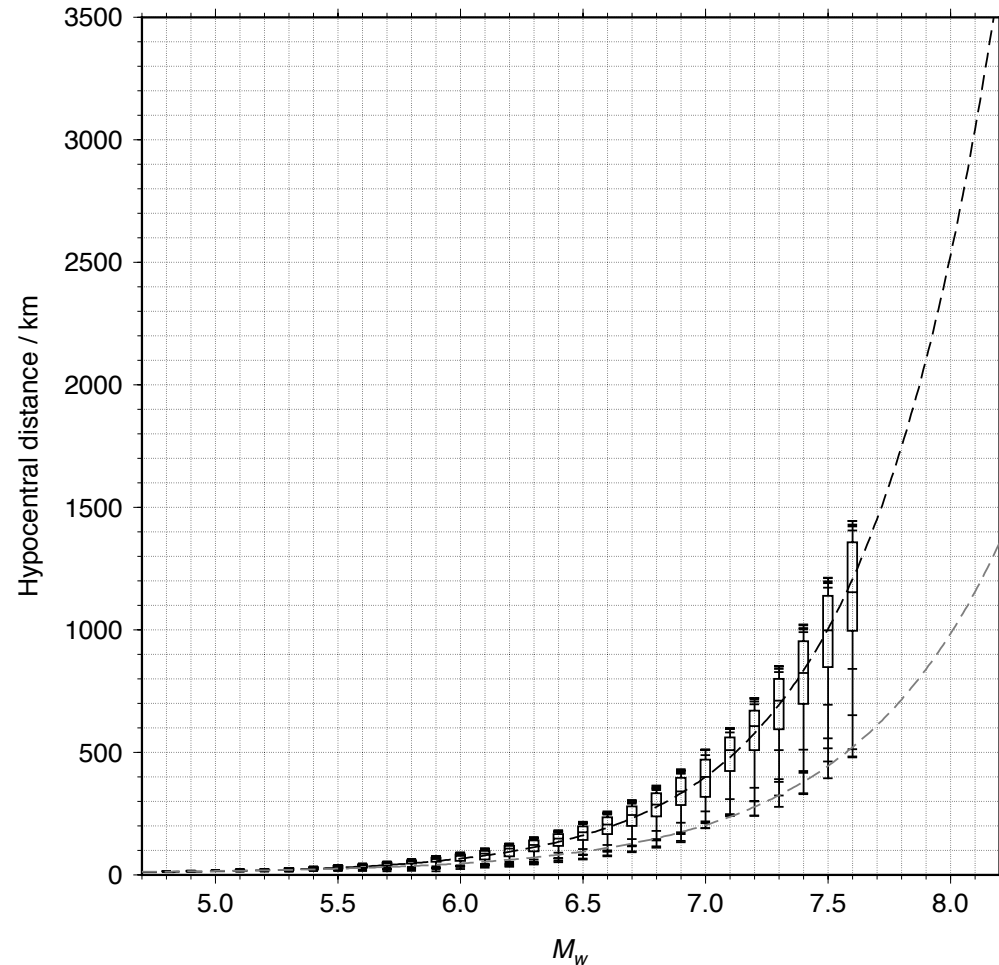
Earthquakes

- Earthquakes occur at known times
- May exhibit more than just a discontinuity
- Take care when earthquake occurs in the middle of processing day
 - Some data will fall before and some after ground displacement
 - Time series point on day of earthquake may appear between pre-earthquake and post-earthquake position



Radius of influence

1 mm displacement for 10 km hypocentral depth



- “eq_def” line in eq-file contains earthquake ID (two characters), location, etc.
 - ID is used to substitute last two characters of 8-character site name, e.g. XXXX_GPS → XXXX_GSN
- sh_makeeqdef will search archives (ANSS ComCat or ISC) to generate “eq_def” records

Recommendations

- Know your goals
 - Only fit “nuisance” terms
 - It is usually best not to try to fit signals that you are interested in, e.g. seasonal terms if you are studying these.
- Depending on your goal (e.g. linear tectonic velocities), sometimes you just have to abandon data as it is likely to do more harm than good (rename to xxxx_XPS or xxxx_XCL)
 - Adding large process noise in `g1obk` is one approach but be careful not to make too large
 - GLOBK “`sig_neu`” command can be used for small duration “bad” events

Short- vs long-term time series

- Exactly the same procedure is used for short (e.g. survey) and long (e.g. years of continuous data) time series
- The only difference may be the number and type of input h-files, e.g.
 - Daily survey h-files (short-term time series)
 - Combine into one solution (short-term position combination)
 - Several combined survey files over years (long-term time series)
 - Several combined survey files over years (long-term velocity combination)

tsfit and tsview

- `tsfit` is the command-line tool for fitting time series and generating statistics
 - Input “.pos”-files, optionally .eq-files
 - Fits linear rate and choice of common parameters
 - Periodic terms
 - Discontinuities and earthquakes
 - Post-seismic decays
 - Outputs
 - statistics of fit
 - standard (position and velocity) .apr-files
 - extended (periodic, logarithmic decay, etc.) .apr-files
 - Residuals to fit (“.res”-files)
- `tsview` is an alternative that, via a MATLAB interface, allows interaction

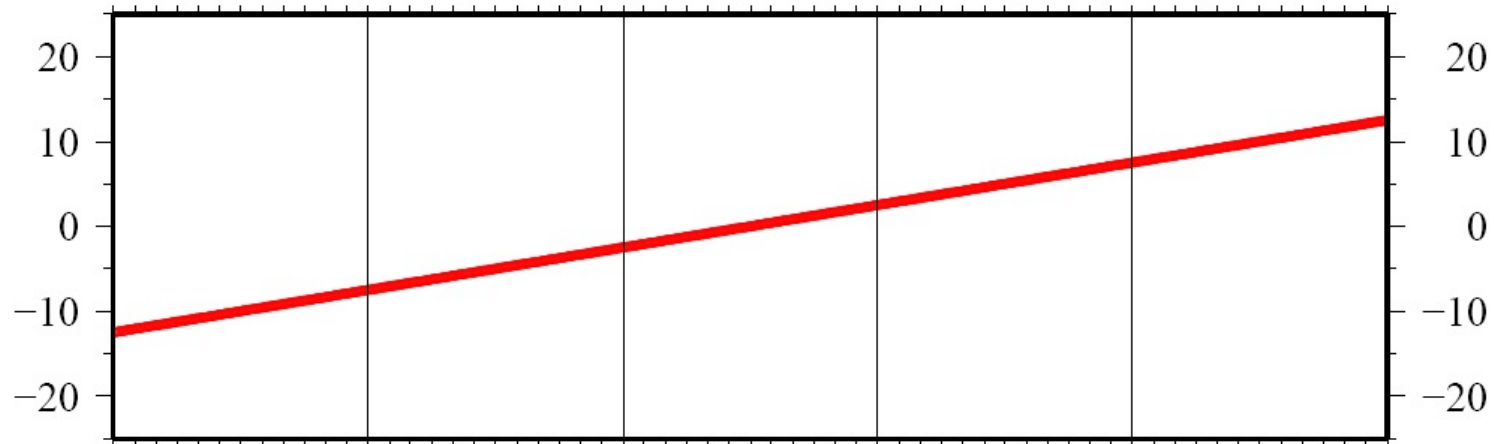
Time series characteristics

Time series components

observed position (linear) velocity term

$$x^i = x_0^i + v^i (t - t_0)$$

initial position

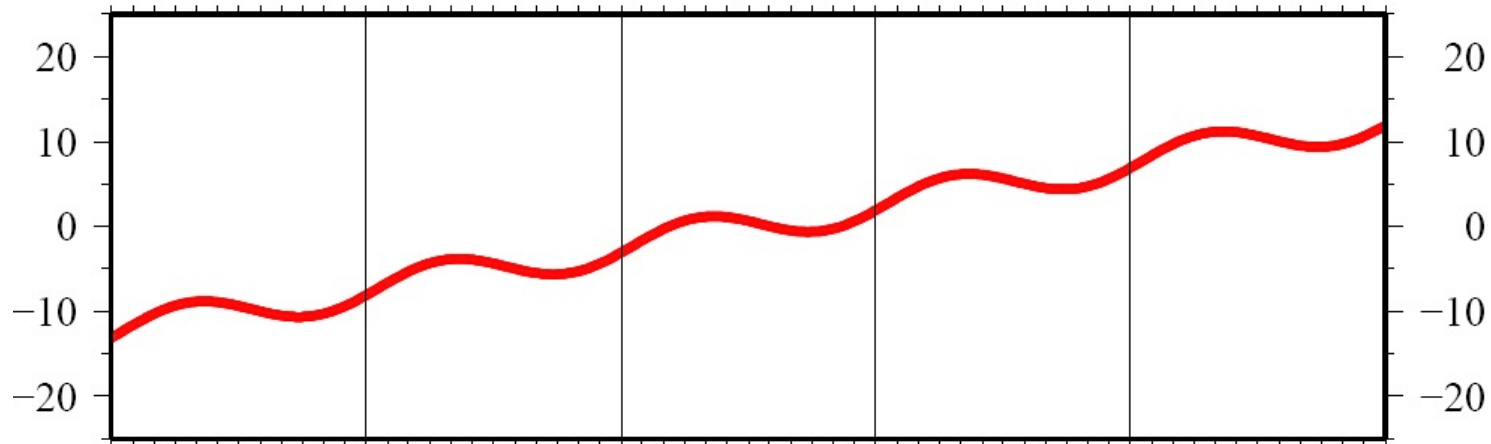


Time series components

observed position (linear) velocity term

$$x^i = x_0^i + v^i(t - t_0) + A_0^i \cos\left(\frac{2\pi(t - t_0)}{T_0} - \tau_0\right)$$

initial position annual period sinusoid



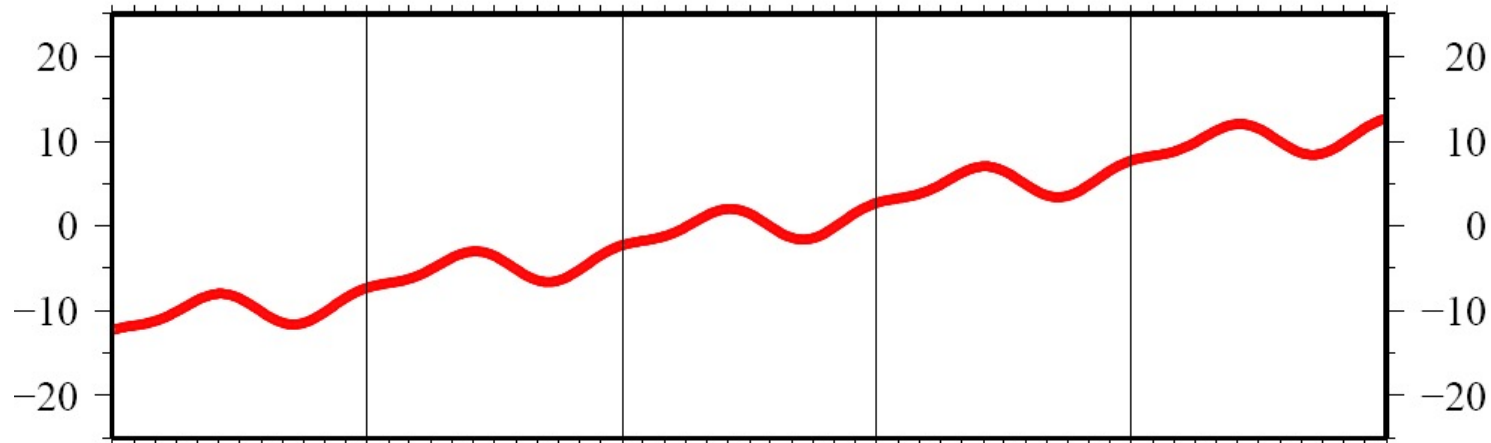
Time series components

observed position (linear) velocity term

$$x^i = x_0^i + v^i(t - t_0) + \underbrace{A_0^i \cos\left(\frac{2\pi(t - t_0)}{T_0} - \tau_0\right)}_{\text{annual period sinusoid}} + \underbrace{A_1^i \cos\left(\frac{2\pi(t - t_0)}{T_1} - \tau_1\right)}_{\text{semi-annual period sinusoid}}$$

initial position

seasonal term



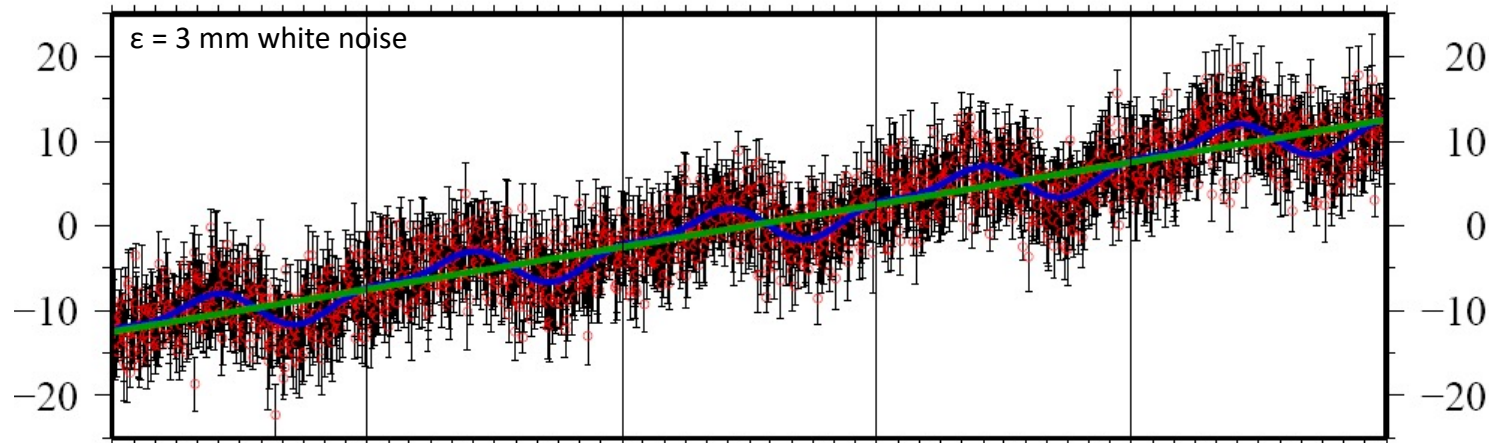
Time series components

observed position (linear) velocity term

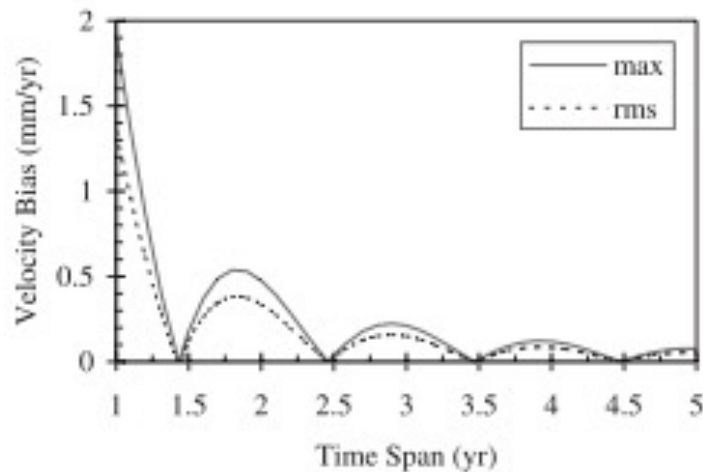
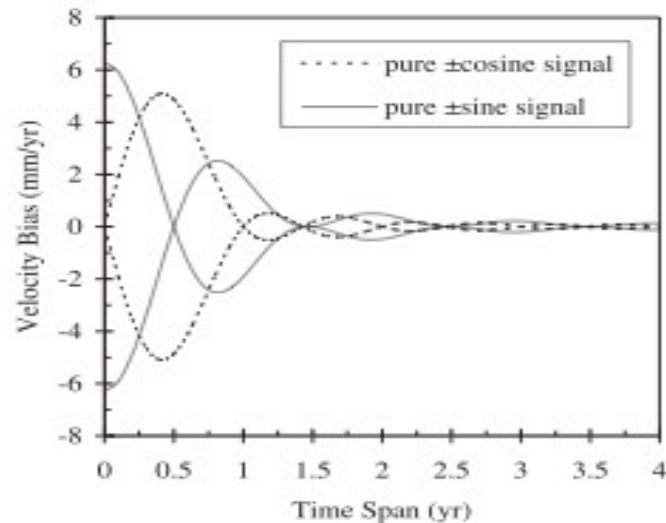
$$x^i = x_0^i + v^i(t - t_0) + \underbrace{A_0^i \cos\left(\frac{2\pi(t - t_0)}{T_0} - \tau_0\right)}_{\text{annual period sinusoid}} + \underbrace{A_1^i \cos\left(\frac{2\pi(t - t_0)}{T_1} - \tau_1\right)}_{\text{semi-annual period sinusoid}} + \varepsilon$$

initial position

seasonal term



Velocity errors due to seasonal signals in continuous time series



- Theoretical analysis of a continuous time series by Blewitt and Lavalée (2002,2003)
- Top: Bias in velocity from a 1mm sinusoidal signal in-phase and with a 90-degree lag with respect to the start of the data span
- Bottom: Maximum and rms velocity bias over all phase angles
 - The minimum bias is NOT obtained with continuous data spanning an even number of years
 - The bias becomes small after 3.5 years of observation

FOGMEx (“realistic sigma”) algorithm for velocity uncertainties

Motivation

- Computational efficiency
- Handle time series with varying lengths and data gaps
- Obtain a model that can be used in `g1obk`

Concept

- The departure from a white-noise (\sqrt{N}) reduction in noise with averaging provides a measure of correlated noise.

Implementation

- Fit the values of χ^2 versus averaging time to the exponential function expected for a first-order Gauss-Markov (FOGM) process (amplitude, correlation time)
- Use the χ^2 value for infinite averaging time predicted from this model to scale the white noise sigma estimates from the original (least-squares) fit
- and/or
- Fit the values to a FOGM with infinite averaging time (i.e., random walk) and use these estimates as input to `g1obk` (“`mar_neu`” command)

sh_cats/sh_hector

- Scripts to aid batch processing of time series with CATS or Hector
- Requires CATS and/or Hector to be pre-installed
- Outputs
 - Velocities in “.vel”-file format
 - Equivalent random walk magnitudes in “mar_neu” commands for sourcing in g1obk command file
- Can take a long time!
- Reads GAMIT/GLOBK formats
 - .pos-file(s) as input
 - .eq-file(s) to define discontinuities for estimation of offsets
 - tsfit command file containing “eq_file”, “max_sigma”, “n_sigma” and/or “periodic” options instead of specifying as sh_cats/sh_hector options
- Writes files for GLOBK
 - .apr-file(s), including “EXTENDED” terms where periodic and/or non-linear (logarithmic and/or exponential decay) terms have been estimated
 - “mar_neu” commands for equivalent random walk process noise

Summary

- `sh_glred` is post-processing equivalent to `sh_gamit`
- `.pos`-file format now standard GLOBK output for time series
- Visual inspection of time series very important for identifying outliers, bad segments of data or other problems like incompatible site IDs
 - `sh_plot_pos` (GMT) and `tsview` (MATLAB)
 - Populate `.eq`-file(s) with “rename” commands or use “sig_neu” commands to mitigate impact of poor or incompatible data points during velocity
 - Be aware that some “outliers” may be stabilization issues if they persist across a large part or all of a network at the same time, so check stabilization using “POS STATISTICS” lines in `.org`-file(s)
 - Numbers of stabilizing sites should be consistent and at least as many as the number of parameters estimated in `glorg` (e.g. three components of rotation and translation)
 - Numbers for `wrms` should be consistent from day-to-day and small (< 5 mm)
- Batch tools are available for longer, denser, continuous time series where point-by-point visual inspection is unreasonable
 - `tsfit` and `tsview`